1 General Overview

This operational manual describes the function of the **AS5000 Programmer** in combination with the programming boards. This tool can program the ams AS5000 series magnetic rotary encoders. The graphical user interface (GUI) runs on PC running Windows XP or later and controls the programmer via the USB interface. All major access modes to the OTP memories can be established. Be aware that ams provides the **AS5000 Programmer** as a reference for programming and reading of mentioned devices (refer to Appendix A) under laboratory conditions (no warranty for mass production).

**Note:** Since firmware version v2.10 the AS5000-Programmer contains a boot loader, which provides an update function for new software release. Please refer to the corresponding application note **AN5000-60** (available on our webpage).

2 Hardware Components

2.1 Description of the Hardware Components

![Figure 1: Three components of the Programmer solution](image)

Figure 1 shows the three components which are needed to program the ams magnetic position sensor. Take care that the connector between programmer and programming board is plugged in the right way.

**Warning:**
In case of wrong connection, the components in the AS5000 programmer or the encoder can be destroyed!
**Figure 2: AS5000 Programmer MRE connector (right side view)**

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Vzap</td>
<td>Programming voltage</td>
</tr>
<tr>
<td>2</td>
<td>Vzap</td>
<td>Programming voltage</td>
</tr>
<tr>
<td>3</td>
<td>D10</td>
<td>Encoder signal</td>
</tr>
<tr>
<td>4</td>
<td>ADC2</td>
<td>Device autodetection voltage</td>
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<tr>
<td>5</td>
<td>D9</td>
<td>Encoder signal</td>
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<tr>
<td>6</td>
<td>ADC1</td>
<td>Vzap feedback</td>
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<tr>
<td>7</td>
<td>D8</td>
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<tr>
<td>10</td>
<td>D6</td>
<td>Encoder signal</td>
</tr>
<tr>
<td>11</td>
<td>VDD</td>
<td>Encoder power supply</td>
</tr>
<tr>
<td>12</td>
<td>VDD</td>
<td>Encoder power supply</td>
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<tr>
<td>13</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>14</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>15</td>
<td>D5</td>
<td>Encoder signal</td>
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<tr>
<td>16</td>
<td>D0</td>
<td>Encoder &amp; LCD display signal</td>
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<td>17</td>
<td>D4</td>
<td>Encoder signal</td>
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<td>18</td>
<td>D1</td>
<td>LCD signal – Do not use</td>
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<td>19</td>
<td>D3</td>
<td>Encoder &amp; LCD display signal</td>
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<td>20</td>
<td>D2</td>
<td>Encoder &amp; LCD display signal</td>
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2.2 Description of the programming board

The programming board (AS5xxx-PB) is specific for a group of devices. By jumper setting on this board the build in firmware in the programming box automatically detects the selected device. It is not recommended to change the jumper setting to a different encoder type than installed in the socket.

To place or remove a device from the socket, push the black frame of the socket down. This socket has more connectors as the AS50xx/AS51xx part and therefore it is important to align the device to the left side of the socket. The pin 1 of the device must be on the bottom left side. Figure 2 shows the detailed placed device in the socket. The jumper J9 is specific for the AS5043/AS5143. This Jumper is used to close the feedback loop used for the analog output operation mode. With this jumper the gain can set to 1.

The jumper J6 is by default closed because the AS5000 Programmer provides 3.3V operation. In case of 5 V operation the jumper must be removed and the configuration can be changed over the GUI.
3 Installation

3.1 Hardware setup

First connect the AS5xxx-PB to the 20-pin connector of the AS5000 Programmer, as shown on Figure 1. The AS5000 Programmer is directly powered by the PC via USB. An external power supply is not needed.

3.2 Installing the GUI on the PC

The preliminary software is developed for a Microsoft Windows XP operating system with Service Pack 2. In addition the dotnet (.NET) framework version 2.0 or more must be installed on the PC. This package can be downloaded free of charge from the Microsoft webpage:


Following Procedure is recommended before starting the GUI:

1. check on your PC if Service Pack 2 is installed
2. install the mentioned .net package to your computer
3. execute AS5000GUI_setup.exe
4. Finally start the GUI using the shortcut in the start menu or desktop.
4 Graphical User Interface (GUI)

Figure 4 shows the main window of the GUI.
In the top left corner, informations about the connected hardware are displayed:
- firmware (FW) type of the connected hardware: ubox (AS5000 Programmer) or dbrd (Demoboard)
- firmware (FW) version

By default the GUI is in the auto detection mode. Any ams device connected on the USB port (one device at the same time) will be automatically detected and displayed in the right top corner.

Note: The autodetect mode can be disabled and forced to any other device type by selecting the device manually.

Once a PB board inserted, tabs will be displayed allowing go into two main sections: SSI (or TWI) and OTP.
4.1 Programming the AS5040/AS5045/AS5140/AS5145/AS5045B

Programming AS5040/AS5140 encoders requires the AS5040-PB ZIF socket board. This adapter is compatible with AS5040, AS5140, AS5045, AS5145 and AS5045B.

Jumper J6 must be close for normal operation and programming operation.

By selecting the SSI tab, information of the angular position and the status bits appear:

- Die selection: This option is for dual die AS52xx devices only. For AS50xx and AS51xx devices Die 0 (default) must be selected.
- Value field is the raw angle extracted from the SSI stream. The angle range is 0° to 1023 (359.6°)
- Status field displays the status bits extracted from the SSI stream. Green light means that the airgap between the magnet and encoder is correct. Orange light means the magnet is too close of too far.
- CCW checkbox is the angle direction. To invert the rotating direction, check CCW.

Figure 5: AS5040-PB Programming board

Figure 6: SSI tab with AS5040 encoder inserted in AS5040-PB
Zero Position field: Set button writes the actual angle value into the Zero Position register of the encoder. This programming is not permanent. The actual value will be 0 after zero position programming. To reset the zero position register, or to set a new zero position, click on Reset first.

- Read interval is the SSI stream readout and refresh rate the GUI.

This example is the effect when the function Zero Position SET has been performed. Before programming, the encoder shows the position 651 (Figure 6). One click on Zero Position Set makes the software writing the value 651 into the OTP Zero Position register (not permanent programming). Selecting Zero Position Reset will write the value 0 to the OTP Zero Position register.

Note: The Zero Position function is the same for all the AS50xx, AS51xx, AS52xx rotary encoders offering this feature.

Selecting the OTP tab will read the OTP configuration from the IC.
Figure 8: OTP tab of an unprogrammed AS5040

**AS5040/AS5045:**
- **Read** reads the OTP configuration from the permanent fuse register.
- **Write** writes the bits checked by the user into the volatile OTP register. Selecting the SSI after the configuration is possible to check the effect of the new configuration.
- **Zap!** writes permanently the checked OTP bits to the encoder’s fuses.

**AS5140/AS5145:**
- **Load** reads the OTP configuration from the permanent fuse register.
- **Read** reads the OTP configuration from the volatile register.
- **Write** writes the bits checked by the user into the volatile OTP register. Selecting the SSI after the configuration is possible to check the effect.
- **Zap!** writes permanently the checked OTP bits to the encoder’s fuses.
4.1 Programming the AS5043

Programming AS5043 encoders requires the AS5043-PB ZIF socket board.

Jumper J6 must be close for normal operation and programming operation.

![Figure 9: AS5043-PB Programming board](image)

By selecting the SSI tab, information of the angular position and the status bits appear:

![Figure 10: SSI tab with AS5043 inserted in AS5043-PB](image)

- Die selection: This option is for dual die AS52xx devices only. For AS50xx and AS51xx devices Die 0 (default) must be selected.
- Value field is the raw angle extracted from the SSI stream. The angle range is 0 (0°) to 1023 (359.6°)
- Status field displays the status bits extracted from the SSI stream. Green light means that the airgap between the magnet and encoder is correct. Orange light means the magnet is too close or too far.
- CCW checkbox is the angle direction. To invert the rotating direction, check CCW.
- Zero Position field: Set button writes the actual angle value into the Zero Position register of the encoder. This programming is not permanent. The actual value will be 0 after zero position programming. To reset the zero position register, or to set a new zero position, click on Reset first.
- Read interval is the SSI stream readout and refresh rate the GUI.

AS5043-PB ZIF socket board

Device selection for autodetect:
- Jumper position 1: AS5043

Selected die (dual die AS52xx devices only)
Status bits and field alarm
Counter Clockwise mode
Set the actual angle as Zero Position
AS5043:

Read reads the OTP configuration from the permanent fuse register.

Write writes the bits checked by the user into the volatile OTP register. Selecting the SSI after the configuration is possible to check the effect of the new configuration.

Zap writes permanently the checked OTP bits to the encoder's fuses.
4.2 Programming the AS5245

Programming AS5245 encoders requires the AS5245-PB socket board.

Jumper J6 (J6+J8 for AS5245) must be close for normal operation and programming operation.

**AS5245-PB ZIF socket board**

Device selection for autodetect:
- Jumper position 2: AS5245

By selecting the SSI tab, information of the angular position and the status bits appear:

- **Die selection**: This option is for dual die AS52xx devices only. For AS50xx and AS51xx devices Die 0 (default) must be selected.
- **Value field** is the raw angle extracted from the SSI stream. The angle range is 0 (0°) to 1023 (359.6°).
- **Status field** displays the status bits extracted from the SSI stream. Green light means that the airgap between the magnet and encoder is correct. Orange light means the magnet is too close or too far.
- **CCW checkbox** is the angle direction. To invert the rotating direction, check CCW.

Position of the magnet

Status bits and field alarm

Counter Clockwise mode

Selected die (dual die AS52xx devices only)

Set the actual angle as Zero Position

Figure 12: AS5245-PB Programming board

Figure 13: SSI tab with AS5045 inserted in AS5040-PB
- Zero Position field: Set button writes the actual angle value into the Zero Position register of the encoder. This programming is not permanent. The actual value will be 0 after zero position programming. To reset the zero position register, or to set a new zero position, click on Reset first.
- Read interval is the SSI stream readout and refresh rate the GUI.

![AS5000 Programmer GUI](image)

**Figure 14: OTP tab of AS5045**

- **AS5245:**
  - **Load** reads the OTP configuration from the permanent fuse register.
  - **Read** reads the OTP configuration from the volatile register.
  - **Write** writes the bits checked by the user into the volatile OTP register. Selecting the SSI after the configuration is possible to check the effect.
  - **Zap** writes permanently the checked OTP bits to the encoder’s fuses.
4.3 Programming the AS5134

Programming AS5134 encoders requires the AS5134-PB socket board.

Figure 15: AS5134-PB Programming Board

AS5134-PB ZIF socket board
Device selection:
- Jumper position 1: AS5134

Figure 16: GUI for the AS5134

- Value field is the raw angle extracted from the interface. The angle range is 0° to 359°.
- Status field (AGC) displays the status bits depending on the set AGC values. Green light means that the airgap between the magnet and encoder is correct. Red light means the magnet is too far away.
- Zero Position field: Set button writes the actual angle value into the Zero Position register of the encoder. This programming is not permanent. The actual value will be 0 after zero position programming. To reset the zero position register, or to set a new zero position, click on Reset first.
- Read interval is the readout and refresh rate the GUI.
- Digital interface opens an additional window (see Figure 17), which provides all communications commands like WRITE_CONFIG or EN_PROG (for entering the extended mode).

![Figure 17: Communication command window](image1.png)

- **AS5134:**
  - **Read** reads the OTP configuration from the permanent fuse register.
  - **Write** writes the bits checked by the user into the volatile OTP register. Selecting the SSI after the configuration is possible to check the effect of the new configuration.
  - **Zap** writes permanently the checked OTP bits to the encoder’s fuses.

![Figure 18: OTP tab of AS5134](image2.png)
Analog Readback is not implemented yet. It will be available soon.
4.4 Programming the AS5163/AS5263

Figure 19: AS5x63-CB Connection Board (left) and AS5163-PB Programming Board (right)

Programming AS5163/AS5263 encoders requires the AS5163-PB/AS5263-PB socket board and the AS5x63-CB connection board. The connection board provides the load, needed for programming and operating the AS5163/AS5263.

Further details concerning all programming options are provided in application note AN5163-10 (available on our webpage).

4.5 Programming the AS5115/AS5215

Figure 20: AS5115-PB Programming Board (left) and AS5215-PB Programming Board (right)
The AS5115-PB and AS5215-PB does not support an angle readback of the analogue outputs.

- **AS5115/AS5215:**
  - **Read** reads the OTP configuration from the permanent fuse register.
  - **Write** writes the bits checked by the user into the volatile OTP register. Selecting the SSI after the configuration is possible to check the effect of the new configuration.
  - **Zap** writes permanently the checked OTP bits to the encoder’s fuses.
5 Programming boards (PB) Schematics

5.1 AS5040-PB-1.1
5.2 AS5043-PB-1.1
5.3 AS5115-PB1.1

Diagram of AS5115-PB1.1 showing connections and pinout.

5.4 AS5134-PB-1.1

Diagram of AS5134 showing connections and pinout with labels for Device Select and Vzap measures.
5.5 AS5163-PB-1.0

5.6 AS5215-PB-1.1

5.7 AS5245-PB-1.1
5.8 AS5263-PB-1.0
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<th>AS5043 PB</th>
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